
Sparse & Redundant Representation

Iterated Shrinkage Algorithms

Wavelet thresholding

We will Talk About

- The minimization of the functional

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{D}\mathbf{a} - \mathbf{x}\|_2^2 + \lambda\rho(\mathbf{a})$$

- Substitution: $\mathbf{u} = \mathbf{D}\mathbf{a}$

and assume \mathbf{D} is invertible $\mathbf{B} = \mathbf{D}^{-1}$: $\mathbf{B}\mathbf{D} = \mathbf{I}$

$$f(\mathbf{u}) = \frac{1}{2} \|\mathbf{u} - \mathbf{x}\|_2^2 + \lambda\rho(\mathbf{B}\mathbf{u})$$

This is our original denoising functional, if

$$\mathbf{B} = \begin{bmatrix} \partial_x \\ \partial_y \end{bmatrix}$$

$$\mathbf{B}^+\mathbf{B} = \mathbf{I}$$

$$\mathbf{D} = \mathbf{B}^+ = (\mathbf{B}^T\mathbf{B})^{-1}\mathbf{B}^T$$

Moore-Penrose pseudoinverse

Why Seeking Sparse Representation?

- Assume \mathbf{x} is 1-sparse signal in the dictionary $\mathbf{D} = [\mathbf{d}_1, \mathbf{d}_2, \dots, \mathbf{d}_p]$

$$\mathbf{D}\mathbf{a} = \mathbf{x} = \begin{array}{|c} \hline \text{red} \\ \hline \end{array} = \begin{array}{|c|c|} \hline \text{red} & \text{red} \\ \hline \end{array}$$

- $\max_i \langle \mathbf{d}_i, \mathbf{x} \rangle$ is the perfect solution
- Overcomplete dictionaries \Rightarrow sparsity

Measure of Sparsity

- l_p , $0 < p \leq 1$ norms ($\|\mathbf{a}\|_p^p$)

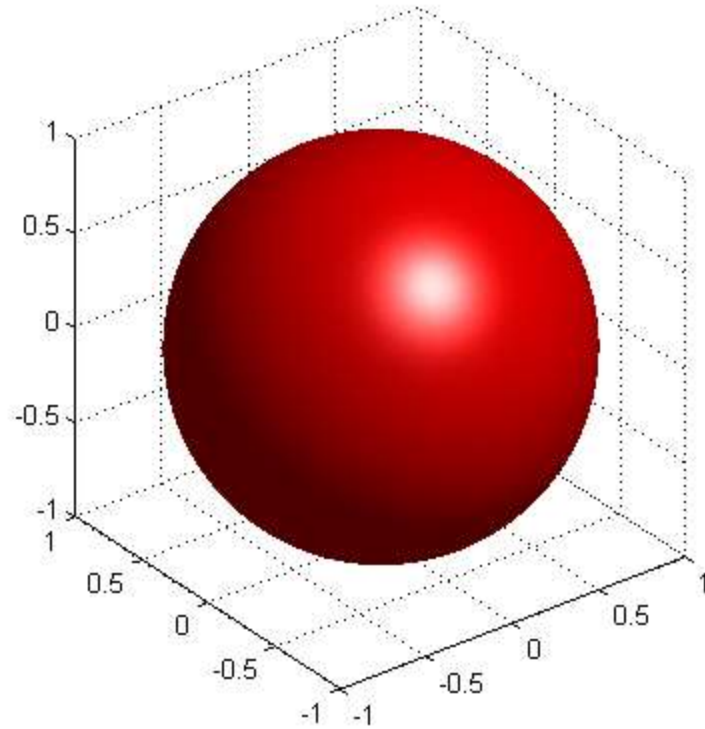
$$\|\mathbf{a}\|_p = \left(\sum_i |a_i|^p \right)^{\frac{1}{p}}$$

- l_0 norm, counts nonzero elements

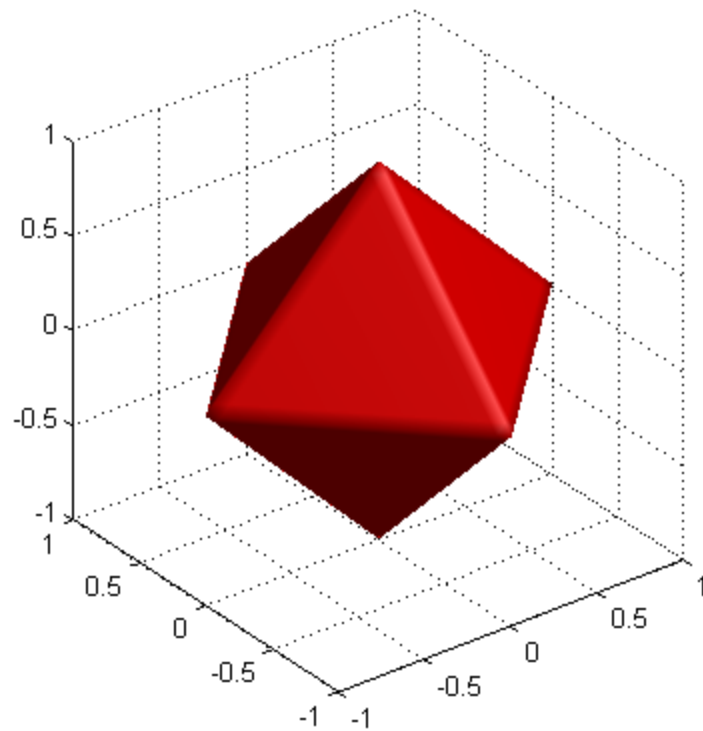
- many other sparsity measures

- smooth l_1 $\rho(\mathbf{a}) = \|\mathbf{a}\|_1 - \epsilon \log \left(1 + \frac{\|\mathbf{a}\|_1}{\epsilon} \right)$

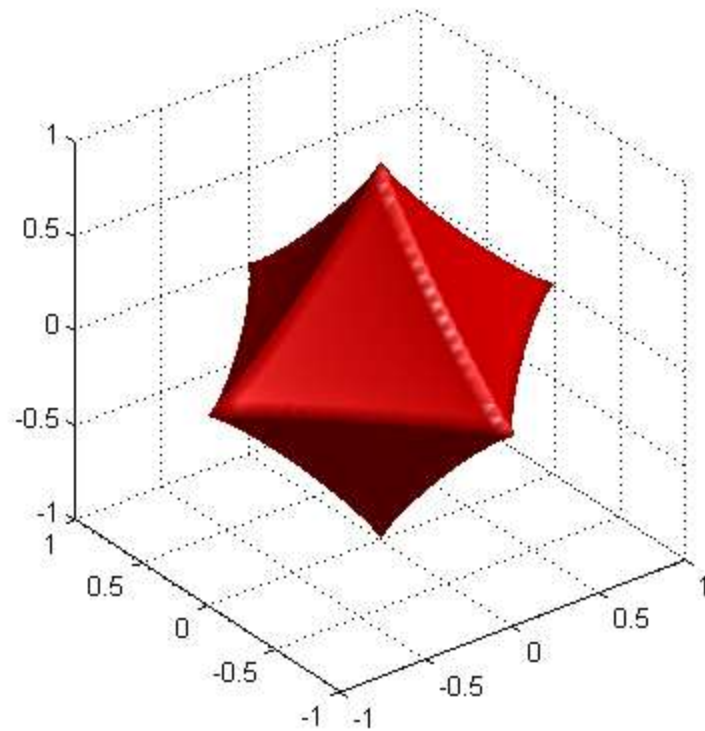
l_2 unit ball



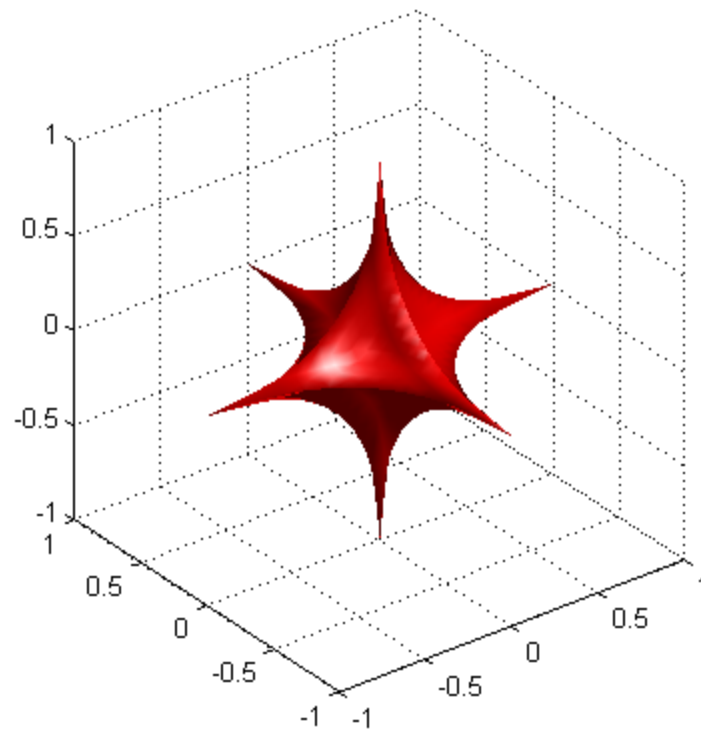
l_1 unit ball



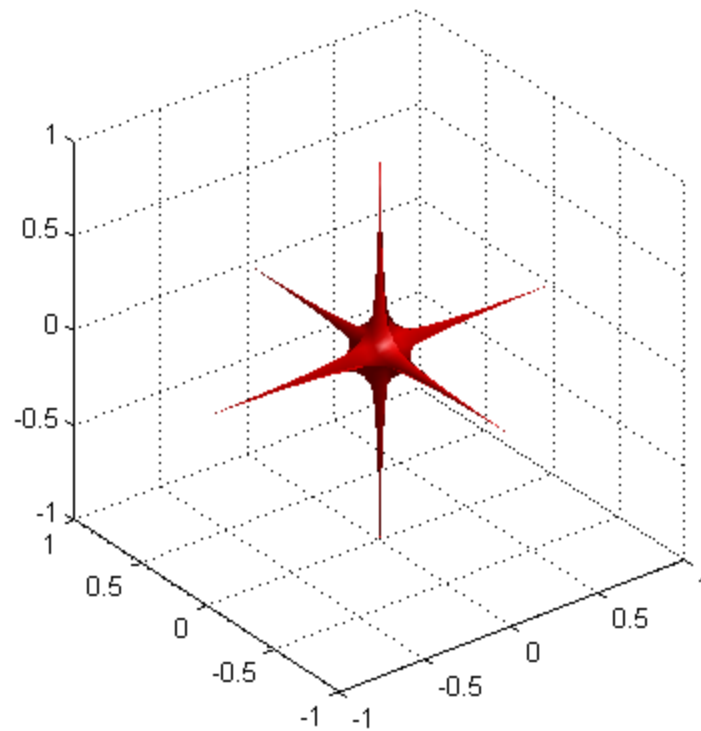
$l_{0.9}$ unit ball



$l_{0.5}$ unit ball



$l_{0.3}$ unit ball



Similar formulation

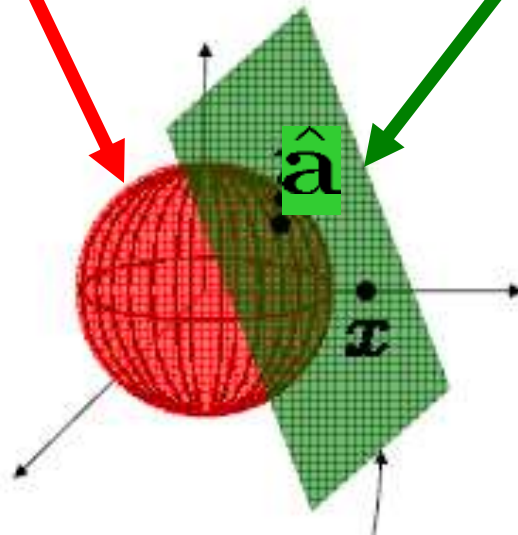
$$\hat{\mathbf{a}} = \arg \min_{\mathbf{a}} \frac{1}{2} \|\mathbf{D}\mathbf{a} - \mathbf{x}\|_2^2 + \lambda \rho(\mathbf{a})$$

- Method of Lagrange multipliers

$$\hat{\mathbf{a}} = \arg \min_{\mathbf{a}} \rho(\mathbf{a}) \quad \text{subject to} \quad \mathbf{D}\mathbf{a} = \mathbf{x}$$

l_2 -norm

$$\hat{\mathbf{a}} = \arg \min_{\mathbf{a}} \|\mathbf{a}\|_2^2 \quad \text{subject to} \quad \mathbf{D}\mathbf{a} = \mathbf{x}$$

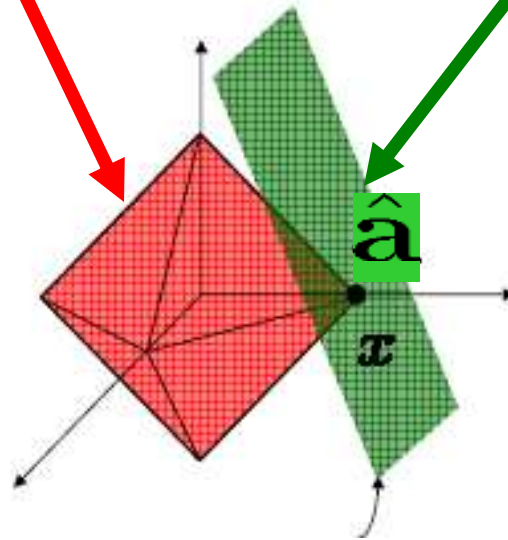


Solution via pseudoinverse is simple but not sparse:

$$\hat{\mathbf{a}} = \mathbf{D}^+ \mathbf{x}$$

l_1 -norm

$$\hat{\mathbf{a}} = \arg \min_{\mathbf{a}} \|\mathbf{a}\|_1 \quad \text{subject to} \quad \mathbf{D}\mathbf{a} = \mathbf{x}$$



Classical Solvers

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{D}\mathbf{a} - \mathbf{x}\|_2^2 + \lambda\rho(\mathbf{a})$$

- Steepest Descent:

$$\hat{\mathbf{a}}_{i+1} = \hat{\mathbf{a}}_i - \mu \nabla f(\mathbf{a})|_{\hat{\mathbf{a}}_i} = \hat{\mathbf{a}}_i - \mu [\mathbf{D}^T (\mathbf{D}\hat{\mathbf{a}}_i - \mathbf{x}) + \lambda\rho'(\hat{\mathbf{a}}_i)]$$

- Hessian:

$$\nabla^2 f(\mathbf{a}) = \mathbf{D}^T \mathbf{D} + \lambda\rho''(\mathbf{a})$$

- Convergence depends on the condition number κ of the Hessian: $(\kappa - 1)/(\kappa + 1)$
- Hessian $\nabla^2 f$ is ill-conditioned
=> poor convergence

The Unitary Case ($\mathbf{D}\mathbf{D}^T = \mathbf{I}$)

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{D}\mathbf{a} - \mathbf{x}\|_2^2 + \lambda\rho(\mathbf{a})$$

Use
 $\mathbf{D}\mathbf{D}^T = \mathbf{I}$

Define

$$\mathbf{b} = \mathbf{D}^T \mathbf{x}$$

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{D}\mathbf{a} - \mathbf{D}\mathbf{D}^T \mathbf{x}\|_2^2 + \lambda\rho(\mathbf{a})$$

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{D}(\mathbf{a} - \mathbf{b})\|_2^2 + \lambda\rho(\mathbf{a})$$

l_2 is unitarily
invariant

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{a} - \mathbf{b}\|_2^2 + \lambda\rho(\mathbf{a})$$

We have m
independent
1D optimization
problems

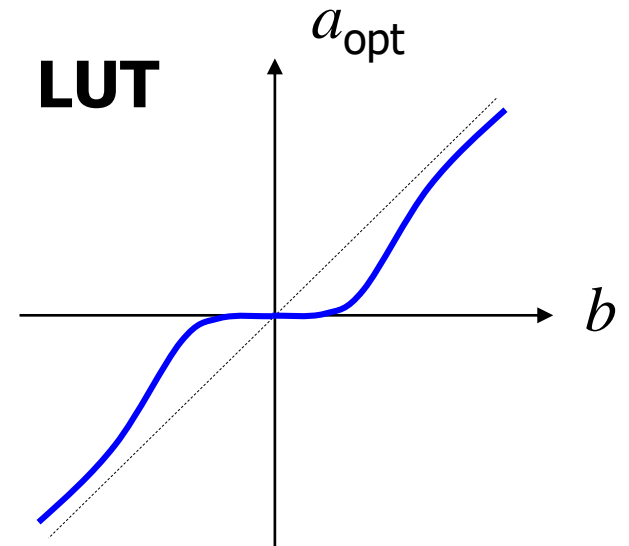
$$= \sum_{i=1}^m \left[\frac{1}{2} (a_i - b_i)^2 + \lambda\rho(a_i) \right]$$

The 1D Task

- We need to solve the following 1D problem:

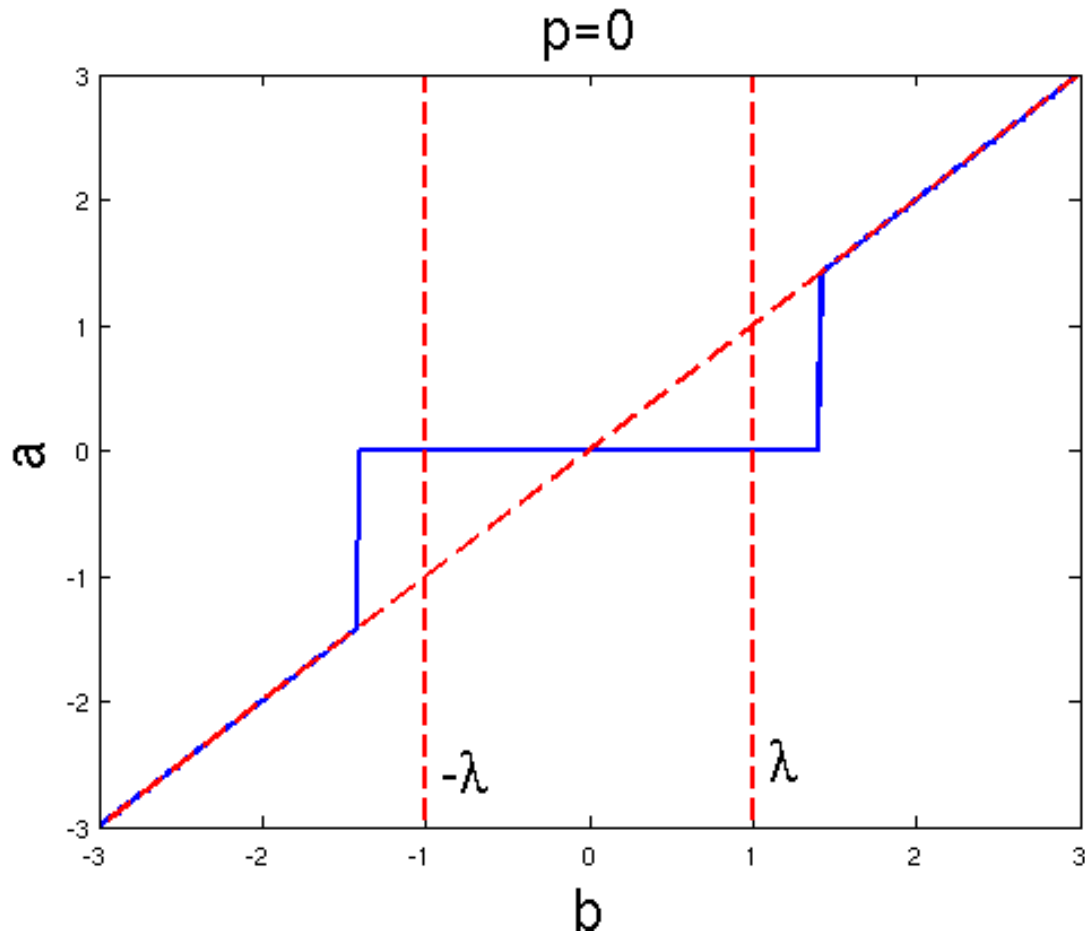
$$a_{\text{opt}} = \arg \min_a \frac{1}{2}(a - b)^2 + \lambda \rho(a)$$

LUT

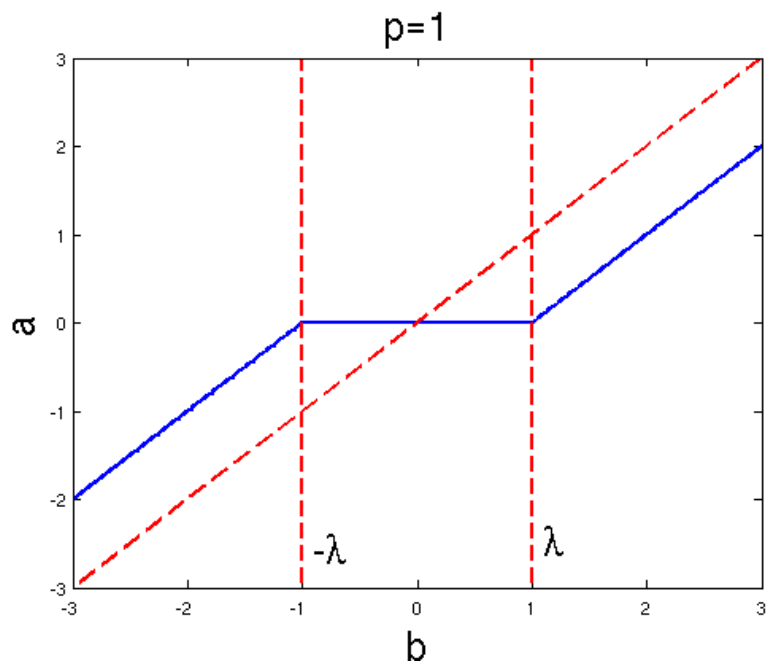


- Such a Look-Up-Table (LUT) $a_{\text{opt}} = S_{\rho, \lambda}(b)$ can be built for **ANY** sparsity measure function $\rho(a)$, including non-convex ones and non-smooth ones (e.g., l_0 norm).

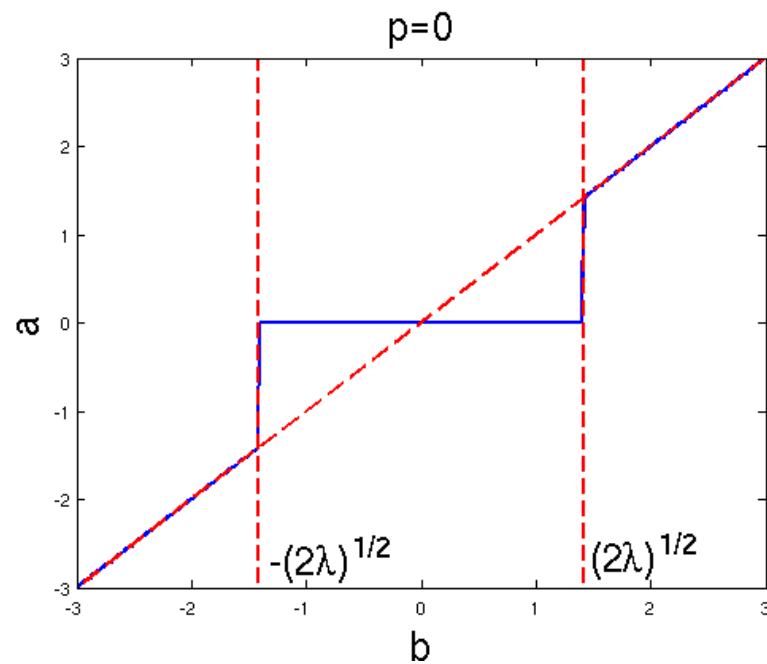
Shrinkage for $\rho(a)=|a|^p$



Soft & Hard Thresholding



Soft thresholding



Hard thresholding

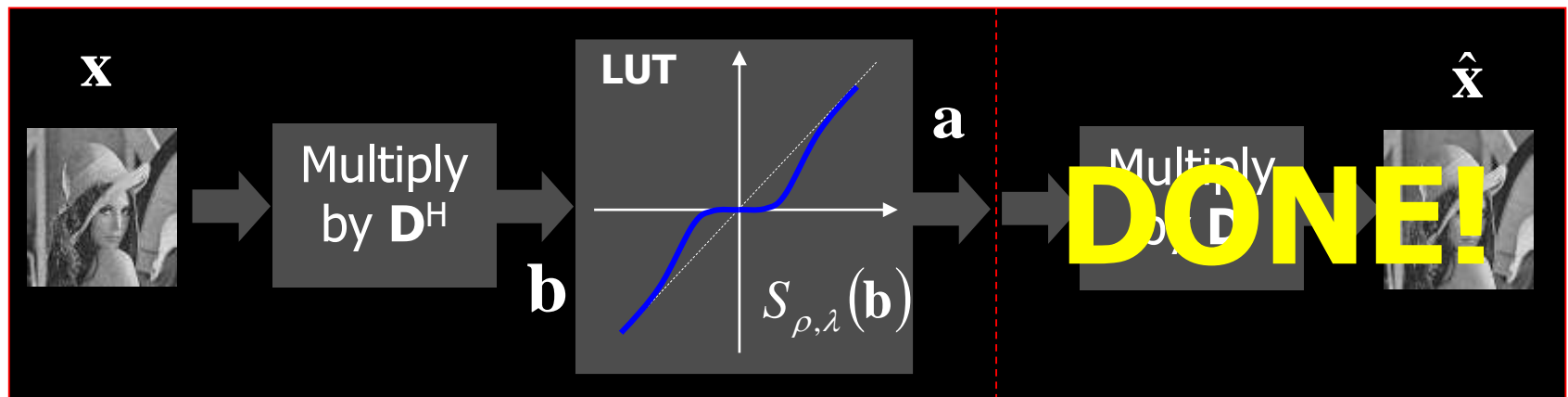
The Unitary Case: Summary

- Minimizing

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{D}\mathbf{a} - \mathbf{x}\|_2^2 + \lambda\rho(\mathbf{a}) = \frac{1}{2} \|\mathbf{a} - \mathbf{b}\|_2^2 + \lambda\rho(\mathbf{a})$$

$$\mathbf{b} = \mathbf{D}^T \mathbf{x}$$

is done by:



Separable case: we achieve GLOBAL minimizer of $f(\mathbf{a})$, even if $f(\mathbf{a})$ is non-convex.

The minimization of

$$f(\mathbf{a}) = \frac{1}{2} \|\mathbf{D}\mathbf{a} - \mathbf{x}\|_2^2 + \lambda\rho(\mathbf{a})$$

Leads to two very **Contradicting Observations**:

1. The problem is **quite hard** – classic optimization find it hard.
2. The problem is **trivial** for the case of unitary **D**.

Solution: Proximal Algorithms

Proximal Operator

$$a^* = \arg \min_a \frac{1}{2\lambda} \|a - b\|_2^2 + \rho(a) = \mathbf{prox}_{\lambda\rho}(b)$$

ex.: indicator function

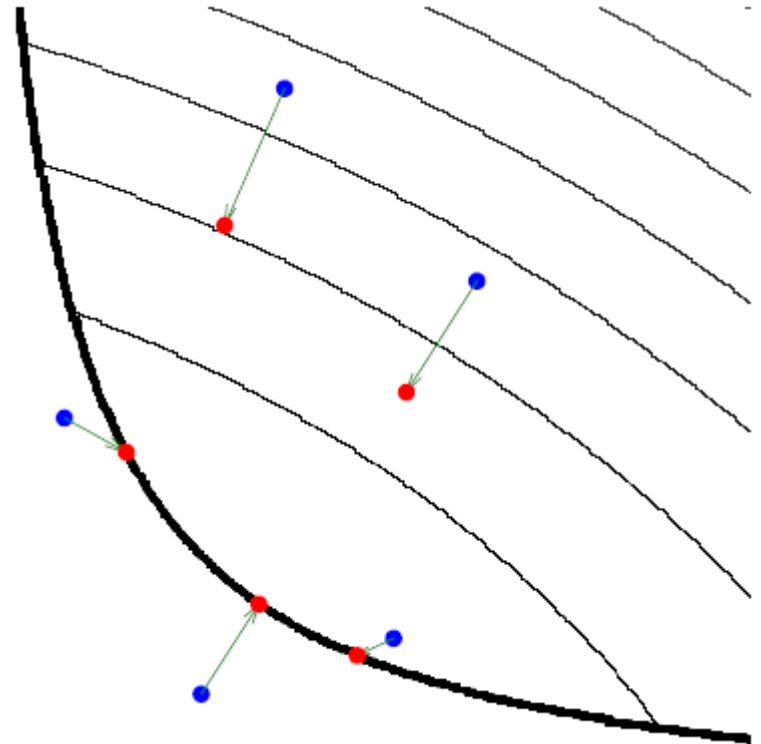
- If $\rho(a)$ closed proper convex

\Rightarrow

$\mathbf{prox}_{\rho}(b)$ strictly convex

\Rightarrow

unique minimizer



Examples of **prox** op.

- L1 norm ->
soft thresholding

$$\rho = \| \cdot \|_1 \rightarrow \mathbf{prox}(b) := S_\lambda(b)$$

- Indicator function of a convex set C ->
projection onto C

$$\rho = I_C \rightarrow \mathbf{prox}(b) := \Pi_C(b)$$